

# Data mining, machine learning, and uncertainty reasoning

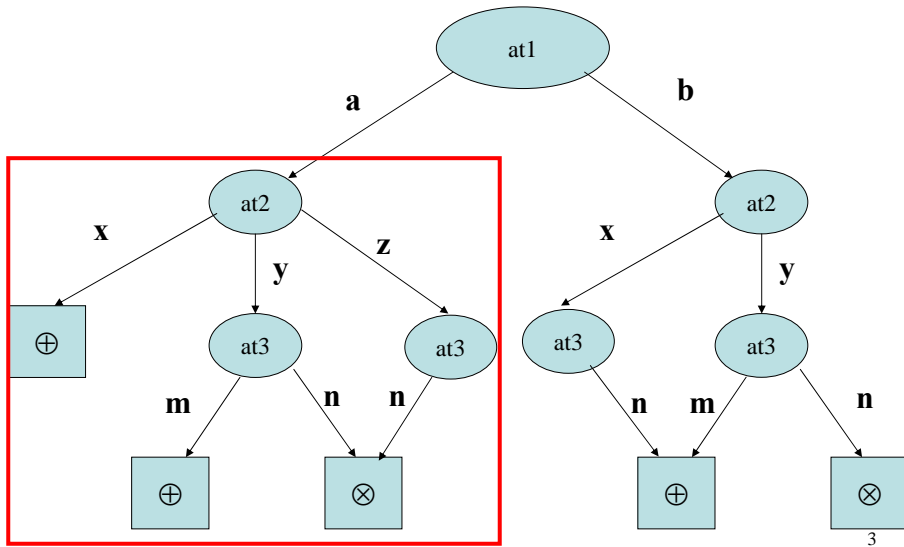
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Positive and negative examples for concept learning

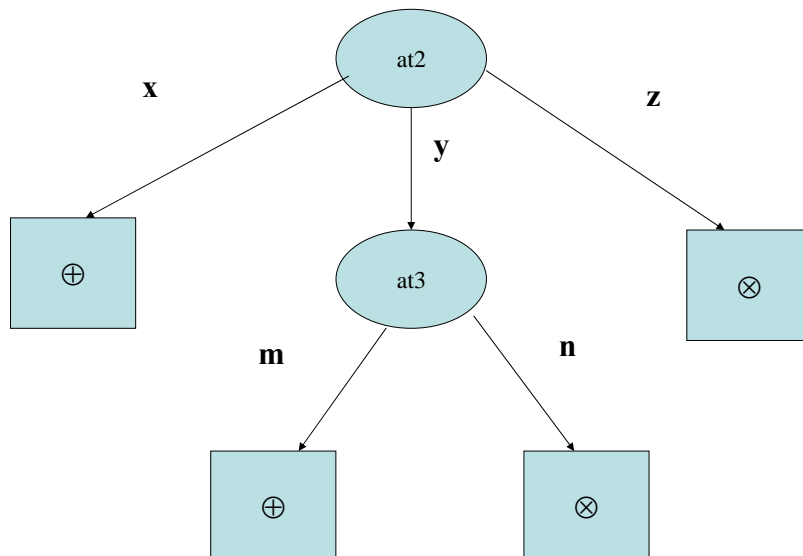
example	at1	at2	at3	Classification
e1	a	x	n	$\oplus$ (positive)
e2	b	x	n	$\oplus$
e3	a	y	n	$\otimes$ (negative)
e4	a	z	n	$\otimes$
e5	a	y	m	$\oplus$
e6	b	y	n	$\otimes$
e7	b	y	m	$\oplus$
e8	a	x	m	$\oplus$



# Decision tree of example table



# Decision tree of example table



# TDIDT Algorithm

S ... the set of examples

1. Find the “best” attribute *at* (***if this can be found!!!***)
2. Split the set S into the subset  $S_1, S_2, \dots$ , so that all examples in the subset  $S_i$  have  $at=v_i$ . Each subset constitutes a node in the decision tree
3. For each  $S_i$  : **if all examples in  $S_i$  belong to the same class ( $\otimes$  or  $\oplus$ ), then create a leaf of the decision tree and label it with this class label (such as x or z) .** Otherwise, perform the same procedure (go to step 1) with  $S=S_i$  (such as *at3*)

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# TDIDT Algorithm

- The entire set of examples is **split into subsets** that are more easy to handle
- With a properly defined **evaluation function**, the TDIDT algorithm will derive the proper **decision tree**
- This **Divide-and-conquer algorithm terminates when all subsets are labeled or when no further attributes splitting the unlabelled sets are available**
- Complete the full **decision tree** can cover the table example but they include some **negative examples**
- The most difficult is **how to find the first best attribute in step 1!!**

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## How to find the best attribute

- The **evaluation function** that is satisfied the following requirements:
  - The function reaches its **maximum** when all subsets are **homogeneous** → all examples in  $S_i$  are  $\otimes$  or all examples in  $S_i$  are  $\oplus$ , the information about the attribute value is sufficient to decide whether the example is **positive** or **negative**
  - The function reaches its **minimum** when **50%** of the examples in each of the subsets are **positive** and **50%** are **negative**
  - The **function** should be **steep** when close to the **extremes** (100% positive or vice versa) and **flat** when in the **50%-50% region**

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## Entropy

- Information is maximized when another important quantity “**entropy**” is minimized
- Entropy determines the extent of **randomness**, “**un-structuredness**”, **chaos** in the data
- The entropy of subset  $S_i$  can be calculated by means of the formula as shown in the next slice
- $P_i^+$  is the probability that a randomly taken example in  $S_i$  is  $\oplus$  and  $n_i^+$  is the number of  $\oplus$  in  $S_i$   $P_i^+ = \frac{n_i^+}{n_i^+ + n_i^-}$
- $P_i^-$  is the probability that a randomly taken example in  $S_i$  is  $\otimes$  and  $n_i^-$  is the number of  $\otimes$  in  $S_i$   $P_i^- = \frac{n_i^-}{n_i^+ + n_i^-}$

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## Entropy formula

$$H(S_i) = -P_i^+ \log P_i^+ - P_i^- \log P_i^-$$

$$P_i^+ = \frac{n_i^+}{n_i^+ + n_i^-}, P_i^- = \frac{n_i^-}{n_i^+ + n_i^-}$$

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## Attribute consideration

- Let the values of attributes *at* split the set S of examples into the subset  $S_i$ ,  $i=1, \dots, k$ , then the entropy of the system of subsets  $S_i$  is :

$$H(S, at) = \sum_{i=1}^k P(S_i) \cdot H(S_i)$$

- $H(S_i)$  is the entropy of the subset  $S_i$ ;  $P(S_i)$  is the probability of an example belonging to  $S_i$  and can be estimated by the relative size of the subset  $S_i$  in S:

$$P(S_i) = \frac{|S_i|}{S}$$

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# Information gain

- **Information gain** achieved by the partitioning along  $at$  is measured by the entailed decrease in entropy:  $I(S, at) = H(S) - H(S, at)$  where  $H(S)$  is the a priori entropy of  $S$  (before splitting) and  $H(S, at)$  is the entropy of the system of subsets generated by the value of  $at$

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## Positive and negative examples for concept learning

example	at1	at2	at3	Classification
e1	a	x	n	$\oplus$ (positive)
e2	b	x	n	$\oplus$
e3	a	y	n	$\otimes$ (negative)
e4	a	z	n	$\otimes$
e5	a	y	m	$\oplus$
e6	b	y	n	$\otimes$
e7	b	y	m	$\oplus$
e8	a	x	m	$\oplus$

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## Computation result

- H(S) **before splitting** the attribute consideration **5 positive** and **3 negative** among 8 examples in S, the **a priori entropy** of the system S is:

$$\begin{aligned} H(S) &= -P^+ \log P^+ + -P^- \log P^- \\ &= -(5/8) \log(5/8) - (3/8) \log(3/8) = \mathbf{0.31025} \end{aligned}$$

- $\log 2 = 0.3010$ ,  $\log 3 = 0.4771$ ,  $\log 4 = 0.6021$ ,  
 $\log 5 = 0.69897$ ,  $\log 6 = 0.77815$ ,  $\log 8 = 0.9031$ ,  
 $\log(5/8) = \log 5 - \log 8 = 0.69897 - 0.9031 = -0.20413$   
 $\log(3/8) = \log 3 - \log 8 = 0.4771 - 0.9031 = -0.426$

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## Computation result

- The number of  $\oplus$  is about the same as the number of  $\otimes$
- If the number of  $\oplus$  were much larger than that of  $\otimes$ , we should have a high chance of a correct guess of the class by simply assuming that it is always  $\oplus$   $\rightarrow$  **this would correspond to small entropy**

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## Entropy of the different partition

- at1 has  $S_a$  and  $S_b$ , it can be computed individually

$$H(S_i) = -P_i^+ \log P_i^+ - P_i^- \log P_i^-$$

$$S_a \text{ has 5 items (3 } \oplus \text{ and 2 } \otimes)$$

$$S_b \text{ has 3 items (2 } \oplus \text{ and 1 } \otimes)$$

$$P_i^+ = \frac{n_i^+}{n_i^+ + n_i^-}, P_i^- = \frac{n_i^-}{n_i^+ + n_i^-}$$

$$H(S, \text{at1}) = \sum_{i=1}^k P(S_i) \cdot H(S_i)$$

- $H(S_a) = -(3/5)\log(3/5) - (2/5)\log(2/5) = 0.29231$   
 $H(S_b) = -(2/3)\log(2/3) - (1/3)\log(1/3) = 0.276$   
 $H(S, \text{at1}) = 5/8 * (0.29231) + 3/8 * (0.276) = 0.28619$

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## Entropy of the different partition

- at3 has  $S_m$  and  $S_n$ , it can be computed individually

$S_m$  has 3 items (3  $\oplus$ )

$S_n$  has 5 items (2  $\oplus$  and 3  $\otimes$ )

$$H(S_m) = -1 \log(1) - 0 \log(0) = 0$$

$$H(S_n) = -(2/5)\log(2/5) - (3/5)\log(3/5) = 0.29231$$

$$H(S, \text{at3}) = 3/8 * (0) + 5/8 * (0.29234) = 0.1826937$$

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## Entropy of the different partition

- at2 has  $S_x$ ,  $S_y$  and  $S_z$ , it can be computed individually

$S_x$  has 3 items (3  $\oplus$ )

$S_y$  has 4 items (2  $\oplus$  and 2  $\otimes$ )

$S_z$  has 1 items (1  $\otimes$ )

$$H(S_x) = -(1)\log(1) - (0)\log(0) = 0$$

$$H(S_y) = -(2/4)\log(2/4) - (2/4)\log(2/4) = 0.3010$$

$$H(S_z) = -(0)\log(0) - (1)\log(1) = 0$$

$$H(S, \text{at2}) = 3/8 * (0) + 1/8 * (0) + 4/8 * (0.3010) = 0.1505$$

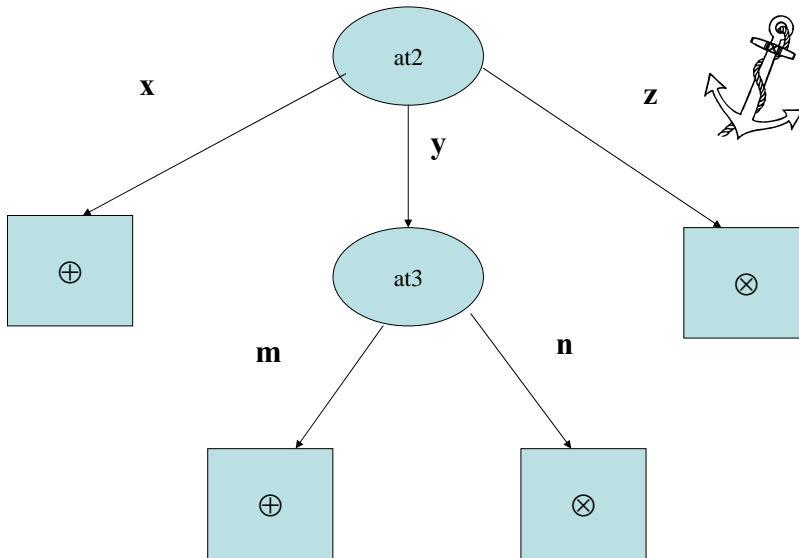
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## Information gain comparison

- $I(S, \text{at1}) = H(S) - H(S, \text{at1})$   
 $= 0.31025 - 0.28619 = 0.02406$
- $I(S, \text{at2}) = H(S) - H(S, \text{at2})$   
 $= 0.31025 - 0.1505 = 0.15975$
- $I(S, \text{at3}) = H(S) - H(S, \text{at3})$   
 $= 0.31025 - 0.1826937 = 0.1275563$
- **at2 has the highest information gain**, and should be selected as **the root of the tree**
- Use of entropy is just one of many possibilities

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## Decision tree of example table



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## Example for homework



example	at1	at2	at3	Classification
e1	y	n	r	⊕
e2	x	m	r	⊕
e3	y	n	s	⊕
e4	x	n	r	⊕
f1	x	m	s	⊗
f2	y	m	t	⊗
f3	y	n	t	⊗
f4	z	n	t	⊗
f5	z	n	r	⊗
f6	x	n	s	⊗

## 計算複雜程度

本班考試成績的平均值，是針對本班所有同學的考試成績而言。所以“平均值”是指的是廣義集合內各個個體的**標誌值的平均值**。

平均值= (每個個體的標誌值的合計值) / 個體總數

$$\rightarrow \bar{X} = \sum_i x_i / N$$

如果廣義集合的個體總數 ( $N$ ) 多於100個，用這種公式求平均值容易出現資料登錄差錯。統計學裏還有其他的計算公式就可以減少錯誤

$$\rightarrow \bar{X} = (\sum_i n_i x_i) / N$$

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## 計算複雜程度

- 60個同學的考試分數(分佈函數值) 為100分有20人，90分有30人，80分有10人，平均值=  
( 20×100+30×90+10×80 ) / 60 =91.67
- 如果用每個同學的分數相加要做60次加法，而這裏僅做了7次計算就得到出了平均值為91.67，這顯然比前一個公式簡單

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## 計算複雜程度

- 平均值 =  $(\sum \text{有該標誌值的個體的數量} \times \text{該標誌值}) / \text{個體總數}$
- 現在把求平均值公式做一些變形就得到了廣義集合的另外一個特徵量 --- 複雜程度。
- 變形 → 平均值的公式裏不是有該標誌值嗎？把它改成“具有該標誌值的個體在總體中占的百分比的對數”
- 平均值公式裏最後不是要用廣義集合內的個體總數 $N$ 來除嗎？現在省去這個計算，但是在公式最前面加個負號

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## 計算複雜程度

- 複雜程度 =  $-\sum \text{每個標誌值的分佈函數值} \times \text{具有該標誌值的個體在總體中占的百分比的對數}$
- 如果用 $C$ 表示複雜程度、用 $n_i$ 表示各個標誌值具有的個體的數量、用 $N$ 表示廣義集合內個體的總數，複雜程度的公式可以寫為  $C = \sum n_i \log\left(\frac{n_i}{N}\right)$
- 仍以學生考試成績為例，學生成績的複雜程度  
 $= -[20 \times \log(20/60) + 30 \times \log(30/60) + 10 \times \log(10/60)] = 26.35$
- 26.35這個數字描述了60個同學考試成績的複雜程度
- 如果全班同學都是清一色的100分。公式計算的結果是學生考試成績的複雜程度 =  $-60 \times \log(60/60) = 0$

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## 複雜程度的單位：bits

- 計算複雜程度的公式中要用“對數”，而對數的值與求對數用什麼為“底”有關。這引導我們從規定“對數的底”是什麼的角度去確定複雜程度的單位。如果規定計算複雜程度時對數都“以2為底”，其複雜程度的單位就稱為“Bit”
- “Bit”是描述資訊存儲量大小的單位。為什麼複雜程度要用電腦界的單位？電腦界借用了表示資訊的單位（Bit）而複雜程度的計算公式與資訊量的計算公式是一致的，所以我們也借用資訊理論中對資訊的計量單位。

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## 複雜程度的單位：bits

- 如果計算時用的是以10位底的對數，也可以用對數換底公式換算成Bit，把以10為底的對數值乘以3.3219就得到了以2為底的對數值(比特值)。即 $\log_2 x = 3.321928 * \log_{10} x$
- 有個例子是擲了1000次的硬幣，正反面朝上的事件各為500次。由這個結局組成的廣義集合的複雜程度301.0 (=  $-[500 \times \log(500/1000) + 500 \times \log(500/1000)] = -1000 \times \log(1/2) = 301.0$ )，把它乘3.321928就得到了以Bit單位的複雜程度，即 $301 \times 3.321928 = 1000 \text{Bit}$ 。

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## 複雜程度的單位：bits

- 對數的計算現在都用電腦或者計數器完成。而對數都是10位底或者以自然數e (2.71828) 為底。所以在一些場合這都要利用對數換底公式去換算成“Bit”。
- 如果直接用以10為底計算對數，得到的複雜程度應當稱為Hartley，以自然數e為底計算對數而得到的複雜程度應當稱為nat。這些單位也是從資訊理論中借來的，但是它們都沒有“Bit”那麼常用。

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## Computation result

- H(S) before splitting the attribute consideration  
5 positive and 3 negative among 8 examples in S,  
the a priori entropy of the system S is:  
$$H(S) = -P^+ \log P^+ + -P^- \log P^-$$
$$= -(5/8) \log(5/8) - (3/8) \log(3/8) = 0.31025$$
- $\log_2 x = 3.321928 * \log_{10} x$
- H(S) = 0.31025 \* 3.321928 = 0.954 bits

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## Entropy of the different partition

- at1 has  $S_a$  and  $S_b$ , it can be computed individually

$S_a$  has 5 items (3  $\oplus$  and 2  $\otimes$ )

$S_b$  has 3 items (2  $\oplus$  and 1  $\otimes$ )

$$H(S_a) = -(3/5)\log(3/5) - (2/5)\log(2/5) = 0.29231$$

$$H(S_b) = -(2/3)\log(2/3) - (1/3)\log(1/3) = 0.276$$

$$H(S, \text{at1}) = 5/8 * (0.29231) + 3/8 * (0.276) = 0.28619 = \\ 0.28619 * 3.321928 = 0.951\text{bits}$$

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## Entropy of the different partition

- at3 has  $S_m$  and  $S_n$ , it can be computed individually

$S_m$  has 3 items (3  $\oplus$ )

$S_n$  has 5 items (2  $\oplus$  and 3  $\otimes$ )

$$H(S_m) = -1 \log(1) - 0 \log(0) = 0$$

$$H(S_n) = -(2/5)\log(2/5) - (3/5)\log(3/5) = 0.29231$$

$$H(S, \text{at3}) = 3/8 * (0) + 5/8 * (0.29234) = 0.1826937 \\ = 0.1826937 * 3.321928 = 0.6069\text{bits}$$

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## Entropy of the different partition

- at2 has  $S_x$ ,  $S_y$  and  $S_z$ , it can be computed individually
  - $S_x$  has 3 items (3  $\oplus$ )
  - $S_y$  has 4 items (2  $\oplus$  and 2  $\otimes$ )
  - $S_z$  has 1 items (1  $\otimes$ )
  - $H(S_x) = -(1)\log(1) - (0)\log(0) = 0$
  - $H(S_y) = -(2/4)\log(2/4) - (2/4)\log(2/4) = 0.3010$
  - $H(S_z) = -(0)\log(0) - (1)\log(1) = 0$
  - $H(S, \text{at2}) = 3/8 * (0) + 1/8 * (0) + 4/8 * (0.3010) = 0.1505$   
 $= 0.1505 * 3.321928 = 0.5\text{bits}$

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## Information gain comparison

- $I(S, \text{at1}) = H(S) - H(S, \text{at1})$   
 $= 0.954 \text{ bits} - 0.951 \text{ bits} = 0.03 \text{ bits}$
- $I(S, \text{at2}) = H(S) - H(S, \text{at2})$   
 $= 0.954 \text{ bits} - 0.5 \text{ bits} = 0.454 \text{ bits}$
- $I(S, \text{at3}) = H(S) - H(S, \text{at3})$   
 $= 0.954 \text{ bits} - 0.6069 \text{ bits} = 0.347 \text{ bits}$
- **at2 has the highest information gain**, and should be selected as **the root of the tree**
- Use of entropy is just one of many possibilities

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## Pruning the trees

- A few **pitfalls** can put the use of a decision tree in question  
→ **over-fitting**
- A **tree branch** (ending with a **class label**) might have been created from examples that are **noisy** → the attribute values or class labels are **erroneous**
- This branch or some of its **decision tests** will be **misleading**
- If the number of attributes is large, the tree may contain tests on random features that are **irrelevant for correct classifications**

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## Pruning the tree

- Very large trees are hard to interpret and the user will perceive them as a **black box representation**
- It may be beneficial to **prune the resulting tree**
- 2 approaches to prune the decision tree
  - **On-line pruning**: stop the tree growing when the **information gain** caused by the partitioning of the example set **falls below a certain threshold**
  - **Post-pruning**: prune out some of the branches after the tree has been completed

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## Tree simplification (On-line pruning)

- Minimal-error pruning aims at pruning the tree to such an extent that the **overall expected classification error** on new examples is minimized → the **classification error** is estimated for each node in the tree
- In the **leaves**, the **error** is estimated using one of the methods for **estimating the probability** that a new object falling into this leaf will be **misclassified**

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## Tree simplification (On-line pruning)

- Suppose that **N** is the number of examples that **end up in the leaf**, and **e** is the number of these examples that are **misclassified** at this leaf. The **Laplace estimate**  $(e+1)/(N+k)$  (where **k** is the number of all the classes) is used to **estimate the expected error**

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## Tree simplification (**On-line pruning**)

- For a **non-leaf node** of the decision tree, its classification error is estimated as the **weighted sum** of the **classification errors** of the node's subtree. The weights are calculated as **relative frequencies of examples** passing from the node into the corresponding sub-trees
- The **non-leaf error estimate** is called a **back-up error** (threshold!!)

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## Tree simplification (**On-line pruning**)

- If the **error estimate** is lower than the **backup error**, the subtrees will be **pruned out**
- The process of **pruning subtrees** starts at the **bottom levels** of the tree and **propagating upwards** as long as the backed-up errors are higher than the 'static estimates'

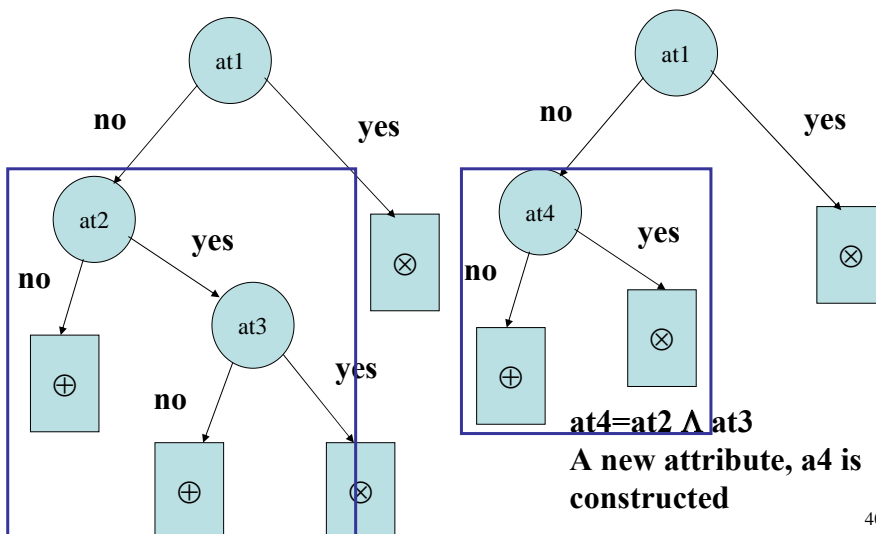
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# Tree simplification

- Another type of tree pruning by carrying out a kind of **constructive induction**
- Learning system strives to create **new attributes** as **logical expressions** over the attributes provided by the **teacher**
- **Constructive induction** can be profitable where a **sub-tree** is replicated in more than one position in the tree

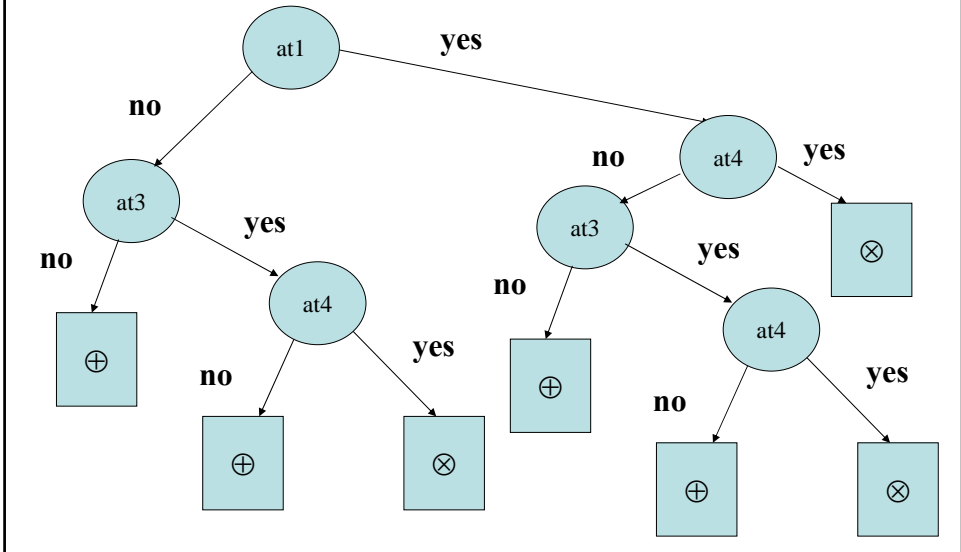
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## Constructive induction in decision tree

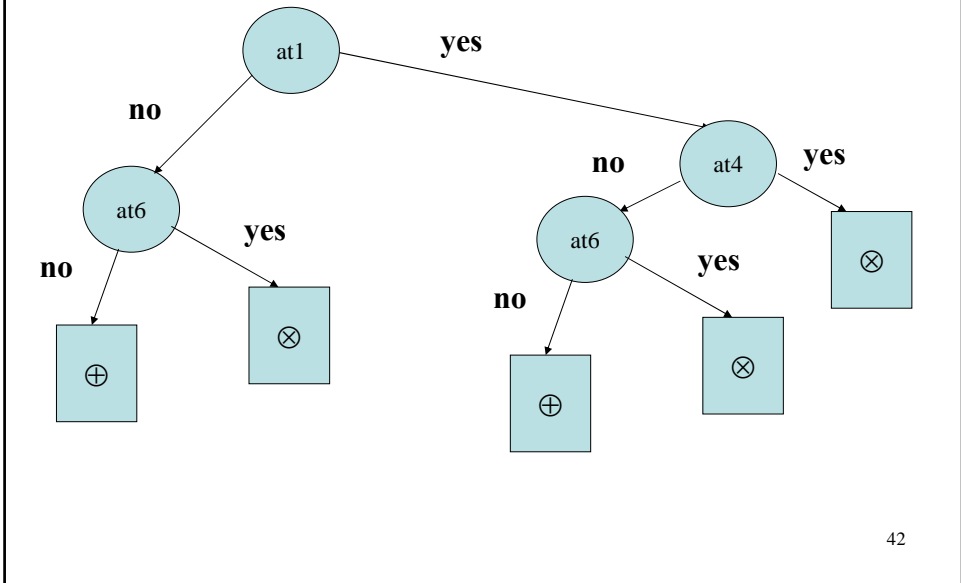


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# The replication problem in decision tree



# Simplified version of a decision tree



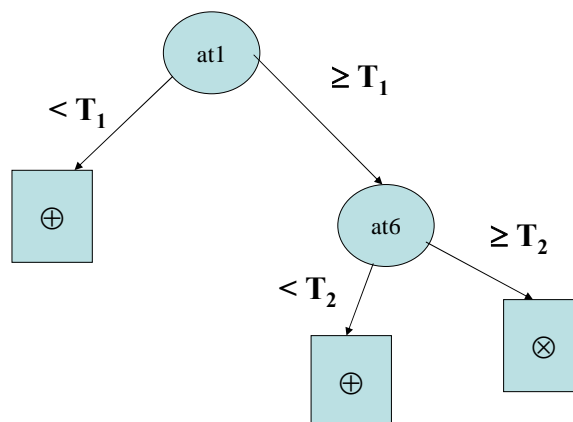
## Threshold position

- Decision trees can also be induced from **numerical** attributes not only **symbolic** attributes
- One possible method is to provide one additional step, the **binarization** of the numerical attributes
- At each node, the respective attribute value is tested against **threshold**  $T_i$
- **Threshold position** in the range of values can be determined by **entropy**
- First order all the examples according to the **best attribute** and observe the classification values

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## Cope with numeric data

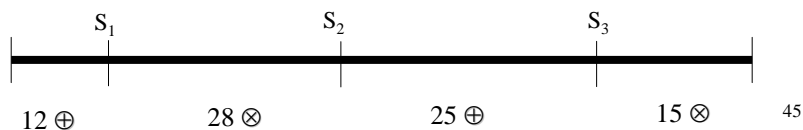
- **Thresholds** the **numerical ranges** into pairs of subintervals to be treated as symbols
- Decision tree built from numeric data as shown



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## Threshold position

- The classification value of  $\oplus$  and  $\otimes$  decompose the set of 80 examples into 4 regions
- The **candidate splitting cuts** lie on the boundaries between the regions  $\rightarrow$  the cut with the **highest information gain** is selected



## Numeric version of TDIDT Algorithm

1. Use the **entropy measure** to find the **optimal split** of the numeric attributes
2. Determine the **attribute** whose **optimal split maximizes entropy** and partition the example set along this attribute into **2 subsets**
3. If the termination criterion is not satisfied, **repeat the procedure recursively** for each subset
4. With each new sub-tree, the **splitting cuts** must be recalculated